

Radamec HK185

Radamec HK185 Robotic Camera Controller

Requirements

- Robotic Camera Control software option
- Serial Interface Cable (DB9 to DB9)

Port Connections

	Switcher		Robotic Camera
Communications	REMOTE Port (female)	⇒	Serial Port
Video	Input BNC	⇒	Output BNC

Cable Connectors

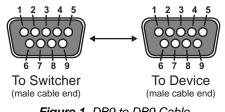


Figure 1 DB9 to DB9 Cable

Pinouts

Switcher	HK185
2 (Rx-)	4 (Tx-)
3 (Tx+)	9 (Rx+)
7 (Rx+)	5 (Tx+)
8 (Tx-)	8 (Rx-)

FlexDevice™ Installation

To Install the FlexDevice Driver

- 1. On your computer, open your Web Browser and, in the address bar, enter the IP address of your frame and press **Enter**.
- Enter your username and password as follows when the Login Dialog Box appears. The default Name is user and Password is password.
- 3. Click Other... ⇒ FlexDevices.
- 4. Click **Browse**. A file selection dialog box is displayed.

- 5. Locate the FlexDevice driver file Robo-Cam_Radamec 1.0-###.tar.gz.
- 6. Click **Open/Choose** to select the file.
- **7.** Click **Install Driver** to upload and install the selected driver to the switcher.

To Initialize the FlexDevice Driver

- 1. Press HOME ⇒ Setup ⇒ Installation ⇒ Com Setup ⇒ FlexDevices.
- 2. Press Start Driver.
- 3. Use the Interface knob to select Panel0.
- 4. Use the Type knob to select FlexCam.
- 5. Use the Driver knob to select Radamec 1.0.
- **6.** Press **Accept**. You must initialize a separate instance of a driver for each device you want to control from the switcher.

Switcher Setup

To Set Up Communications

- Press HOME ⇒ Setup ⇒ Installation ⇒ Com Setup ⇒ Type.
 - Use the **Com Port** knob to select the **REMOTE** *X* port that you connected the HK185 to.
 - Use the **Device** knob to select **FlexCAM**.
- 2. Press Select Device.
 - Use the **Device** knob to select **x_Radamec 1.0**.
- 3. Press Com Type.
 - Use the Type knob to select RS-422.
- 4. Press Com Settings.
 - Use the Baud knob to select 9600.
 - Use the **Parity** knob to select **ODD**.
- 5. Press Extra Options.

Extra Options	Value
Panel ID	5 (default)
Poll	All (default)
Pan/Tilt Damping	5 (default)
Pan/Tilt Speed	64 (default)
Zoom Speed	40 (default)
Focus Speed	15 (default)



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Extra Options	Value
Z Speed	64 (default)

6. Press **HOME** \Rightarrow **Confirm**.

To Set Up Video Inputs

- Press HOME ⇒ Setup ⇒ Installation ⇒ BNC ⇒ BNC Type.
 - Use the **BNC** knob to select the input BNC that the Video output of the camera being controlled by the HK185 is connected to.
 - Use the **Type** knob to select **Robotic Cam**.
 - Use the **Video Format** knob to select the video format of the video output of the camera.

2. Press More ⇒ Camera Setup.

- Use the **Controller** knob to select the port that the HK185 is connected to.
- Use the **Port** knob to select the port on the HK185 that the camera is connected to.
- 3. Press Camera Options and use the knobs to set the options.

Option	Description
Pan Invert	Use the Value knob to invert the direction that the camera moves when using the positioner (Yes), or not (No).
Tilt Invert	Use the Value knob to invert the direction that the camera moves when using the positioner (Yes), or not (No).
Zoom Invert	Use the Value knob to invert the direction that the camera zooms when using the positioner (Yes), or not (No).
Focus Invert	Use the Value knob to invert the focus direction when using the positioner (Yes), or not (No).
Iris Invert	Use the Value knob to invert the iris direction when using the positioner (Yes), or not (No).
X Invert	Use the Value knob to invert the direction that the camera moves in the X-axis when using the positioner (Yes), or not (No).
Y Invert	Use the Value knob to invert the direction that the camera moves in the Y-axis when using the positioner (Yes), or not (No).
Z Invert	Use the Value knob to invert the direction that the camera moves in the Z-axis when using the positioner (Yes), or not (No).

Compatibility

Robotic Camera	Version
Radamec HK185	
FlexDevice	
Radamec FlexCam Driver	1.0
MultiPanel	
MultiPanel Support	*
Automation	
OverDrive	12.0
Port Expanders	
BSS4	×
Comtrol DeviceMaster	✓

4. Press HOME \Rightarrow Confirm.



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